

L Number	Hits	Search Text	DB	Time stamp
1	107	(neural adj network) with (PD or PID)	USPAT; US-PGPUB	2004/09/11 18:19
2	51	((neural adj network) with (PD or PID)) and (700/\$.ccls. or 706/\$.ccls.)	USPAT; US-PGPUB	2004/09/11 18:32
3	22	(neural adj network) with (PD)	USPAT; US-PGPUB	2004/09/11 18:16
4	12	((neural adj network) with (PD)) and (700/\$.ccls. or 706/\$.ccls.)	USPAT; US-PGPUB	2004/09/11 18:16
5	6	((neural adj network) with (PD or PID)) and (aircraft or airplane) and (angul\$4 or angl\$4)	USPAT; US-PGPUB	2004/09/11 18:20
6	12	((neural adj network) with (PD or PID)) and (aircraft or airplane)	USPAT; US-PGPUB	2004/09/11 18:31
7	5260	((aircraft or airplane) with flight with control\$5)	USPAT; US-PGPUB	2004/09/11 18:51
8	85	((aircraft or airplane) with flight with control\$5)) same (inver\$5)	USPAT; US-PGPUB	2004/09/11 18:37
9	7	((aircraft or airplane) with flight with control\$5)) same (inver\$5)) and (700/\$.ccls. or 706/\$.ccls.)	USPAT; US-PGPUB	2004/09/11 18:32
10	280	((aircraft or airplane) with flight with control\$5)) and ((inver\$5) with control\$5)	USPAT; US-PGPUB	2004/09/11 18:37
11	76	((aircraft or airplane) with flight with control\$5)) and ((inver\$5) with control\$5)) and 701/\$.ccls.	USPAT; US-PGPUB	2004/09/11 18:40
12	38	((aircraft or airplane) with flight with control\$5)) and ((inver\$5) with control\$5)) and 701/\$.ccls.) and trim\$4	USPAT; US-PGPUB	2004/09/11 18:42
13	36	((aircraft or airplane) with flight with control\$5)) and ((inver\$5) with control\$5)) and 701/\$.ccls.) and trim\$4) and (attitude or altitude)	USPAT; US-PGPUB	2004/09/11 18:49
14	23	((aircraft or airplane) with flight with control\$5)) and ((inver\$5) with control\$5)) and 701/\$.ccls.) and trim\$4) and (attitude or altitude)) and inertia\$5	USPAT; US-PGPUB	2004/09/11 18:49
15	1247	((aircraft or airplane) with flight with control\$5).clm.	USPAT; US-PGPUB	2004/09/11 18:51
16	4	((aircraft or airplane) with flight with control\$5).clm.) and (inver\$5 and inertia\$4).clm.	USPAT; US-PGPUB	2004/09/11 18:58
17	0	(inverse adj model) same (PD) same (neural adj network) same filter\$4	USPAT; US-PGPUB	2004/09/11 18:59
18	0	(inverse adj model) same controller same (neural adj network) same filter\$4	USPAT; US-PGPUB	2004/09/11 18:59
19	8	(inverse adj model) same controller same (neural adj network)	USPAT; US-PGPUB	2004/09/11 19:00
20	12	(inverse adj model) with (neural adj network)	USPAT; US-PGPUB	2004/09/11 19:01
21	332	(inverse adj model)	USPAT; US-PGPUB	2004/09/11 19:16
22	26	((inverse adj model) ) and ((aircraft) with control\$4)	USPAT; US-PGPUB	2004/09/11 19:16
23	17	((inverse adj model) ) and ((aircraft) with control\$4)) and deriv\$7	USPAT; US-PGPUB	2004/09/11 19:15
24	0	((inverse adj model) ) and ((aircraft) with control\$4)) and deriv\$7) and nueral	USPAT; US-PGPUB	2004/09/11 19:05
25	2	((inverse adj model) ) and ((aircraft) with control\$4)) and deriv\$7) and neural	USPAT; US-PGPUB	2004/09/11 19:05
26	332	inverse adj model	USPAT; US-PGPUB	2004/09/11 19:15
27	70	((inverse adj model) ) and (neural adj network)	USPAT; US-PGPUB	2004/09/11 19:16
28	4	((inverse adj model) ) and (neural adj network)) and (PID or PD)	USPAT; US-PGPUB	2004/09/11 19:16
29	2	((inverse adj model) ) and (neural adj network)) and (PD)	USPAT; US-PGPUB	2004/09/11 19:50
30	1	5213282.pn. and inertia\$3	USPAT; US-PGPUB	2004/09/11 19:50

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